

2.5 Use the weak statement formulation to find solutions to the equation

$$\frac{d^2 u}{dx^2} = 1, \quad 0 < x < 1$$

$$u(0) = 0, \quad \left. \frac{du}{dx} \right|_{x=1} = 1$$

(a) Using linear interpolation functions, as explained in Section 2.3, use (i) one element and (ii) two elements.

(b) Using simple polynomial functions that satisfy the boundary conditions at the left-hand side, i.e.,

(i)  $u(x) = a_1 x$ , hence  $\phi_1(x) = W_1(x) = x$

(ii)  $u(x) = a_1 x + a_2 x^2$ , hence  $\phi_1(x) = W_1(x) = x$ ,

$$\phi_2(x) = W_2(x) = x^2.$$

(c) Using circular functions that satisfy the boundary conditions at the left-hand side, i.e.,

(i)  $u(x) = a_1 \sin(\pi/2 Lx)$

(ii)  $u(x) = a_1 \sin(\pi/2 Lx) + a_2 \sin(3\pi/2 Lx)$

(d) Find the analytical solution and compare with results from (a), (b) and (c).

**Solution**

a) The residual function is  $R(u, x) = \frac{d^2 u}{dx^2} + 1$  The weak form after integration by parts is

$$\int_0^1 \left( \frac{dW}{dx} \frac{du}{dx} + W \right) dx - W \frac{du}{dx} \Big|_0^1 = 0$$

i)

One element solution  $\phi_1 = 1 - x \quad \phi_2 = x$

$$u(x) = (1 - x) a_1 + x a_2$$

$$\int_0^1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \end{bmatrix} dx \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} + \int_0^1 \begin{bmatrix} 1 - x \\ x \end{bmatrix} dx - \begin{Bmatrix} 0 \\ 1 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

Integrating

$$a_1 - a_2 = -1/2$$

$$-a_1 + a_2 = 1/2$$

$$\text{since } a_1 = 0 \quad \text{then } a_2 = 1/2 \quad \text{or } u(x) = x/2$$

ii)

Two element solution. Element 1:

$$\phi_1 = 1 - 2x \quad \phi_2 = 2x$$

$$\int_0^{1/2} \begin{bmatrix} -2 \\ 2 \end{bmatrix} \begin{bmatrix} -2 & 2 \end{bmatrix} dx \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} + \int_0^{1/2} \begin{bmatrix} 1-2x \\ 2x \end{bmatrix} dx \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \quad \text{or} \quad \begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} -1/4 \\ -1/4 \end{Bmatrix}$$

Element 2

$$\phi_2 = 2(1-x) \quad \phi_3 = 2(x-1/2)$$

$$\int_{1/2}^1 \begin{bmatrix} -2 \\ 2 \end{bmatrix} \begin{bmatrix} -2 & 2 \end{bmatrix} dx \begin{Bmatrix} a_2 \\ a_3 \end{Bmatrix} + \int_{1/2}^1 \begin{bmatrix} 2(1-x) \\ 2(x-1/2) \end{bmatrix} dx \begin{Bmatrix} 0 \\ 1 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \quad \text{or} \quad \begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix} \begin{Bmatrix} a_2 \\ a_3 \end{Bmatrix} = \begin{Bmatrix} -1/4 \\ 3/4 \end{Bmatrix}$$

Assemble

the

elements

$$\begin{bmatrix} 2 & -2 & 0 \\ -2 & 4 & -2 \\ 0 & -2 & 2 \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \\ a_3 \end{Bmatrix} = \begin{Bmatrix} -1/4 \\ -1/2 \\ 3/4 \end{Bmatrix} \quad \text{since } a_1 = 0 \text{ we get } a_2 = 1/8 \text{ and } a_3 = 1/2$$

$$u(x) = \begin{cases} x/4 & 0 \leq x \leq 1/2 \\ \frac{3x-1}{4} & 1/2 \leq x \leq 1 \end{cases}$$

b)

Using polynomials

i)

$$\phi_1 = x \quad u(x) = a_1 x$$

$$\int_0^1 (1 \cdot a_1 + x) dx - 1 = 0, \quad a_1 = 1/2, \quad u(x) = x/2, \text{ same as using one element.}$$

ii)

$$\phi_1 = x, \quad \phi_2 = x^2, \quad u(x) = a_1 x + a_2 x^2$$

$$\text{For } W = \phi_1 \quad \int_0^1 [1 \cdot (a_1 + 2a_2 x) + x] dx - 1 = 0$$

$$\text{For } W = \phi_2 \quad \int_0^1 [2x \cdot (a_1 + 2a_2 x) + x^2] dx - 1 = 0$$

The system becomes

$$a_1 + a_2 = 1/2$$

$$a_1 + \frac{4}{3}a_2 = 2/3$$

or

$$a_1 = 0, \quad a_2 = 1/2 \quad \text{and} \quad u(x) = x^2/2$$

c)

Using circular functions

i)

$$\phi_1 = \sin\left(\frac{\pi}{2}x\right) \quad , \quad u(x) = a_1 \sin\left(\frac{\pi}{2}x\right) \quad , \quad \phi'_1 = \frac{\pi}{2} \cos\left(\frac{\pi}{2}x\right)$$

$$\int_0^1 \left[ \frac{\pi^2}{4} a_1 \cos^2\left(\frac{\pi}{2}x\right) + \sin\left(\frac{\pi}{2}x\right) \right] dx - \sin\left(\frac{\pi}{2}x\right) \frac{du}{dx} \Big|_0^1 = 0$$

Use the identities  $\int \cos^2 \alpha x dx = \frac{1}{2\alpha} (\sin \alpha x \cos \alpha x - \alpha x)$  and  $\int \sin\left(\frac{\pi}{2}x\right) dx = -\frac{2}{\pi} \cos\left(\frac{\pi}{2}x\right)$ . Then

$$\frac{\pi^2 a_1}{4} \left( \sin\left(\frac{\pi}{2}x\right) \cos\left(\frac{\pi}{2}x\right) - \frac{x}{2} \right) \Big|_0^1 + \left( -\frac{2}{\pi} \cos\left(\frac{\pi}{2}x\right) \right) \Big|_0^1 - \sin\left(\frac{\pi}{2}x\right) \frac{du}{dx} \Big|_0^1 = 0 \quad \text{or}$$

$$\frac{\pi^2 a_1}{8} + \frac{2}{\pi} - 1 = 0 \quad \text{hence} \quad a_1 \approx 0.295 \quad \text{and} \quad u(x) = 0.295 \sin\left(\frac{\pi}{2}x\right)$$

ii)

$$\phi_2 = \sin\left(\frac{3\pi}{2}x\right) \quad , \quad u(x) = a_1 \sin\left(\frac{\pi}{2}x\right) + a_2 \sin\left(\frac{3\pi}{2}x\right).$$

$$\text{For } W = \phi_1 : \quad \int_0^1 \left[ \frac{\pi^2}{4} \cos\left(\frac{\pi}{2}x\right) \left( a_1 \cos\left(\frac{\pi}{2}x\right) + a_2 \cos\left(\frac{3\pi}{2}x\right) \right) + \sin\left(\frac{\pi}{2}x\right) \right] dx - \sin\left(\frac{\pi}{2}x\right) \frac{du}{dx} \Big|_0^1 = 0$$

$$\text{For } W = \phi_2 : \quad \int_0^1 \left[ 3 \frac{\pi^2}{4} \cos\left(\frac{3\pi}{2}x\right) \left( a_1 \cos\left(\frac{\pi}{2}x\right) + a_2 \cos\left(\frac{3\pi}{2}x\right) \right) + \sin\left(\frac{3\pi}{2}x\right) \right] dx - \sin\left(\frac{3\pi}{2}x\right) \frac{du}{dx} \Big|_0^1 =$$

$$\frac{\pi^2}{8} a_1 + 0 \cdot a_2 + \frac{2}{\pi} - 1 = 0 \quad (a_1 \text{ is unchanged})$$

$$0 \cdot a_1 + \frac{9\pi^2}{8} a_2 + \frac{2}{3\pi} + 1 = 0 \quad , \quad a_2 \approx -0.109 \quad \text{and}$$

$$u(x) \approx 0.295 \sin\left(\frac{\pi}{2}x\right) - 0.109 \sin\left(\frac{3\pi}{2}x\right)$$

d)

Analytical

solution

$$\frac{d^2 u}{dx^2} = 1 \quad , \text{integrating} \quad u(x) = \frac{x^2}{2} + c_1 x + c_2 \quad \text{and applying boundary conditions} \quad u^*(x) = \frac{x^2}{2}.$$

Notice that all the approximations are exact at  $x = 1/2$ , and the Galerkin approximations using  $x$  and  $x^2$  both yield the exact solution. Also notice that the boundary condition at  $x = 1$  is satisfied only approximately. In case a), the first solution gives  $\left. \frac{du}{dx} \right|_{x=1} = \frac{1}{2}$  and the second solution gives

$\left. \frac{du}{dx} \right|_{x=1} = \frac{3}{4}$  which is getting better. This point is discussed in more detail in problem 2.6.